

Improvement of Committee Machine Performance to Solve Multiple Response Optimization Problems

Seyed Jafar Golestaneh^{*1}, Napsiah Ismail², Say Hong Tang³, Mohd Khairol Anuar M. Ariffin⁴, Hassan Moslemi Naeini⁵

^{1,2,3,4} Department of Mechanical and Manufacturing Engineering, Universiti Putra Malaysia, 43400 Serdang, Selangor, Malaysia.

⁵ Faculty of Engineering, Tarbiat Modares University, P.O. Box 14155-143 Tehran, Iran

¹ Industrial Engineering PhD student, Corresponding author, shgol@yahoo.com

¹ Mechanical Engineering PhD, napsiah@eng.upm.edu.my

¹ Mechanical Engineering PhD, saihong@eng.upm.edu.my

¹ Mechanical Engineering PhD, Khairol@eng.upm.edu.my

¹ Mechanical Engineering PhD, moslemi@modares.ac.ir

Abstract-- Three phases are considered for multiple response optimization (MRO) problems. They are design of experiments, modeling and optimization. Committee machines (CM) as a set of some experts such as some artificial neural networks (ANNs) can be applied for modeling phase. Then, genetic algorithm (GA) determines the final solution with object maximizing the global desirability as optimization phase. That algorithm was implemented on five MRO case studies include target, minimizing and maximizing objects. Current article is a development of recent authors' work on application of CM in MRO problem solving. Initial approach in that work, includes a committee machine with four different ANNs. The CM weights are specified with GA which its fitness function was minimizing the overall RMSE for each response. In current work, a new approach was applied in finding the committee machine weights. The fitness function in this approach is made by minimizing the absolute error between CM responses and real data for each response, separately. A performance index is defined to evaluate different models performance. The results from five case studies show that there are noticeable decreasing in overall RMSE whereas there is a negligible decreasing in GD for new CM with respect to initial CM. This is due that less error is a confirmation of performance increasing for new committee machine.

Index Term-- Global desirability, Committee Machine, Multiple responses optimization, Genetic Algorithm

I. INTRODUCTION

Current study is a development in authors recent works [1]. It bodes application of committee machine in modeling of Multiple Response Optimization (MRO) problems. MRO would like to find a set of input variable amounts (x's) which yields a desired set of outputs (y's). MRO as usual is solved in three phases include experiments design, modeling and optimization.

Experiments design is arranged based on some known patterns in Design of Experiments (DOE) knowledge such as factorial design, fraction factorial design. Some designs in Response Surface Methodology (RSM) such as Central Composite

Design (CCD) and Box Behnken [2, 3]. Also, Taguchi orthogonal arrays [4-7] which is derived from Taguchi method.

Second phase is done by means of different mathematical or statistical modeling such as multiple linear and nonlinear regression in the form of polynomials [2, 8, 9] and Artificial Neural Networks (ANNs). Due to the fact that relationship between inputs and outputs usually are complicated, ANNs mostly are used for modeling rather than polynomials. A typical Artificial Neural Network (ANN) is Back Propagation Neural Network (BPNN) that is used in many engineering problems [10, 11]. Cheng et al. [12] used MANFIS (Multi Adaptive Neuro Fuzzy Inference System) for modeling and showed the results are superior to RSM polynomial models.

Last phase is optimization that usually is done on global desirability function. In this process, every predicted response is converted to a value between 0 to 1 by a function with name desirability function. So for all responses, a composite function is defined which converts all desirability functions to a unique number by global desirability function (GDF). Then with optimization of GDF, optimum or optimal values of independent parameters could be found. Different optimization techniques were used to optimize GDF, for example Excel solver, search methods such as Hook and Jeeves [2], Evolutionary Algorithms such as Genetic algorithm [9, 11] and Tabu Search [10]. Also, Chatsirirungruang and Miyakawa [13] proposed a combination of GA with Taguchi and have used benefits of these techniques together to get more accurate responses.

II. SCOPE AND LIMITATIONS

This investigation was established on five real cases from literature. There are different forms of objectives for multiple response optimization problems. They are "Target", "Minimum", "Maximum" and "In rang" objectives. As a limitation, current study and cases involve all objects except

"In rang" and this can be a good area to develop this approach in future. This article shows application of committee machine in multiple response optimization can decrease modeling errors and increase reliability of global desirability prediction. on the other hand this work introduce a container which includes different neural networks methods and also traditional modeling method or multiple regression. so due to its capacity to accept newer methods in future, capability of this approach can be increase with progress in time and method.

Artificial neural networks and Committee Machine

There are different kinds of neural networks to model and apply in complicated prediction problems. This study has considered four neural networks. They are Feed Forward Neural Networks (FF)[14], Radial Basis function networks (RBFN) [15], Generalized Regression neural network (GRNN)[16] also, Adaptive Neural Fuzzy Inference System (ANFIS) [17, 18].

A Committee Machine (CM) consists of a group of intelligent systems named Experts, and a combiner, which combines the outputs of each expert (Figure 1). Its advantages are that it reaps the benefits of all work with only little additional computation. Inputs are entered to experts, and all experts' responses are transferred to a combiner to get final response.

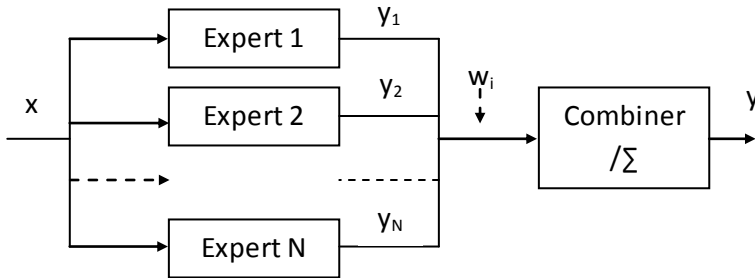


Fig. 1. A typical architecture of a committee machine based on static structure

To combine the experts' outputs, there are different ways in the combiner. It could be an intelligent system such as a neural network. The most popular method is the simple ensemble averaging method according to equation 1[19].

$$y = \sum_{i=1}^N w_i \cdot y_i \tag{1}$$

Where N is the total number of the experts used, w_i is the weight coefficient of i th expert and y_i is the estimated response from i th expert [20].

Genetic Algorithm could be obtained combination of the experts' contribution (weights) in a committee machine. Equation 2, represents committee machine gives smaller errors than the average of all the experts[20, 21].

$$Error_{CM} = \xi \left[\frac{1}{N} \sum_{i=1}^N e_i^2 \right] \leq \frac{1}{N} \sum_{i=1}^N \xi [e_i^2] = Error_{ave} \tag{2}$$

$e_i = y_{i_ANN} - y_{i_real}$ is error of predicted and real response of every ANN or expert. e_i^2 is squared error for the i th expert. $Error_{ave}$ is the average error for each of the experts acting alone. $Error_{CM}$ is error of CM.

Genetic algorithm and global desirability

Genetic Algorithm (GA) can quickly and reliably solve problems that are difficult to tackle by traditional methods. It is extensible and can interface with existing models and hybridize with them and optimizes the fitness function. [22]; [23].

Global desirability Function is used to convert a problem of multiple responses into a single response case. By desirability function, each estimated response is converted into a dimensionless desirability value d_i . For different situations, d_i values are defined by the continuous function which are shown in table I [24, 25].

TABLE I
DESIRABILITY FUNCTIONS FORMULA WITH DIFFERENT OBJECTS

$d_i(y_i) =$	$\begin{cases} 0 & y_i \leq L_i \\ \left(\frac{y_i - L_i}{T_i - L_i}\right)^s & L_i \leq y_i \leq T_i \\ \left(\frac{U_i - y_i}{T_i - U_i}\right)^t & T_i \leq y_i \leq U_i \\ 0 & y_i \geq U_i \end{cases} \tag{3}$	(3)
The desirability for goal of "Target"		
$d_i(y_i) =$	$\begin{cases} 0 & y_i \leq L_i \\ \left(\frac{y_i - L_i}{U_i - L_i}\right)^s & L_i \leq y_i \leq U_i \\ 1 & y_i \geq U_i \end{cases} \tag{4}$	(4)
The desirability for goal of "Maximum"		
$d_i(y_i) =$	$\begin{cases} 1 & y_i \leq L_i \\ \left(\frac{U_i - y_i}{U_i - L_i}\right)^s & L_i < y_i < U_i \\ 0 & y_i \geq U_i \end{cases} \tag{5}$	(5)
The desirability for goal of "Minimum"		

The parameters s and t in formulas in table 1 are convexity coefficients and specify how strictly target value will be desired. In current study, both of them are equal to one. Global desirability (GD) is defined as equation 6:

$$GD = \sqrt[N]{\prod_{j=1}^N d_j} \quad (6)$$

Equations of 3 to 5, yields the desirability for different objects and equation 6 calculates the global desirability (GD). The d_i 's range varies from zero to one, and respectively GD rang is from 0 to 1. Important notice is that optimization of GD depends to all desirabilities and thus denoted as simultaneous optimization of all responses.

III. METHODOLOGY

Dixit and Chandra [26] have suggested a selection method for training data sets for ANNs. They represented for n input, the minimum number of training set should be such that it includes the corners of n -dimensional space with respect to more contribution for input variables with more influence on output. But in current research, this offer was applied for corners of lower and upper limits for all variables. Training to test data numbers was 80-20 percent.

There are different criteria to assess forecasting models performance. In current work two criteria were selected to compare simulated results from models and the observed or real data. They are Root mean square error (RMSE), [27], correlation coefficient (R) [28].

$$RMSE = \sqrt{\left(\frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2\right)} \quad (7)$$

$$R = \frac{\sum_{i=1}^N (y_i - \bar{y})(\hat{y}_i - \bar{\hat{y}})}{\sqrt{\left(\sum_{i=1}^N (y_i - \bar{y})^2 \cdot (\hat{y}_i - \bar{\hat{y}})^2\right)}} \quad (8)$$

$-1 \leq R \leq +1$

\hat{y}_i is i th predicted value (model output), y_i is the i th actual value, and n is the number of data used for prediction. Also \bar{y} and $\bar{\hat{y}}$ are the mean of actual and predicted values. [29]. There are two conditions to build ANNs model in the current work. The first condition is that RMSE for all data be minimum. The Second condition is that correlation coefficient of testing data is positive.

As it is mentioned, MRO solution includes three phases. First, Design of Experiments phase which in the current work, all data is selected from literatures. Second, modeling which is done by building four different neural networks include feed forward, RBF, GRNN and one ANFIS models. All ANNs have same inputs and one output and so the number of ANNs in every model is equal to the number of responses (Figure 2) [1].

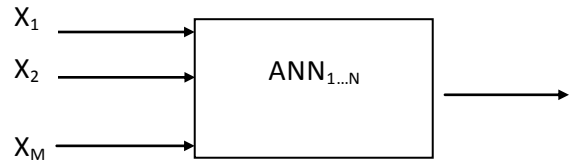


Fig. 2. Input and Outputs of every model

A committee machine (CM) was established by combination of all four models (Figure 3). M Inputs are entered to every expert of CM simultaneously, and N responses are multiplied to their weights and then are added together to get final response. CM combiner is an ensemble averaging. CM weights were determined by Genetic Algorithm (GA) with the object to minimize absolute error between real data and CM response for each response separately. So the total number of weights is 4 multiply by No. of ys (N) multiply by No. of experiments (r).

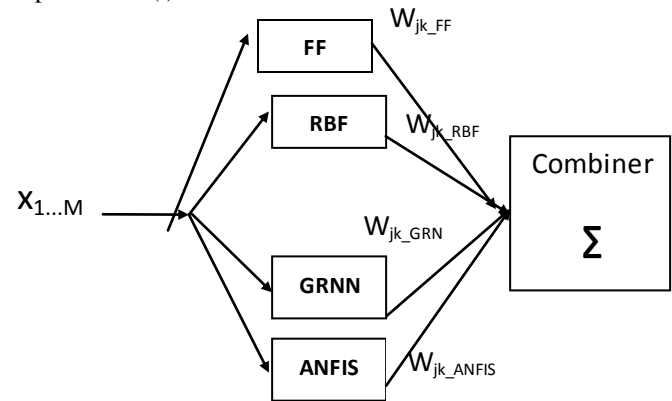


Fig. 3. Committee Machine architecture

Current article is a development of recent authors' work on application of CM in MRO problem solving. Initial approach in that work, includes a committee machine with four different ANNs. The CM weights are specified with GA which its fitness function is minimizing the overall RMSE for each response. Then, another GA determines the final solution with object maximizing the global desirability.

According to current algorithm, firstly, all ANNs are created separately to solve the MRO problem. In the modeling phase, first committee machine (CM) weights are calculated by means of GA with the object of minimizing absolute error between real responses and CM responses for each response, separately. Then as optimization phase, GA gets best responses with the object of maximizing global desirability.

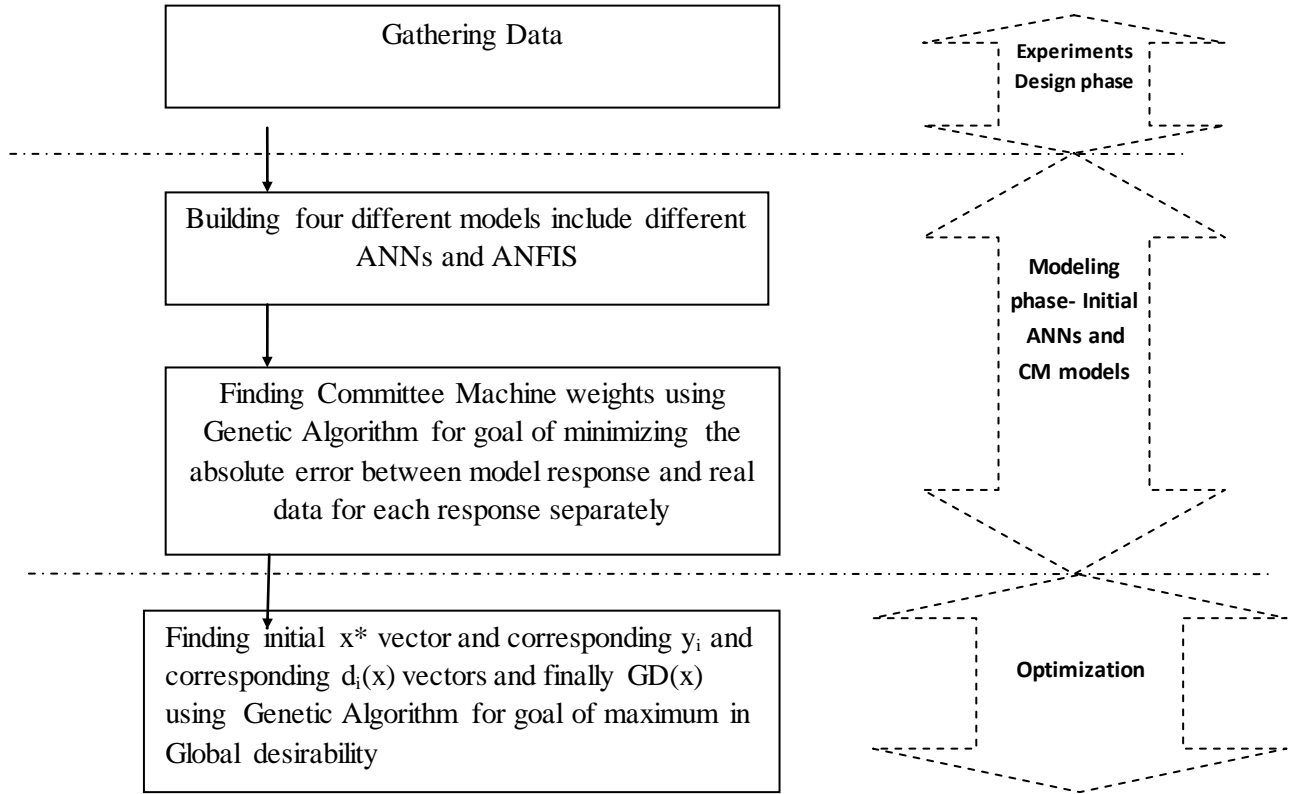


Fig. 4. Research Methodology

To evaluate performance CMs, a model performance index (P index) is defined as formula 9. Then for all models, the P index is calculated.

$$\text{Performance Index}_{\text{model}} = \frac{\text{GD}_{\text{model}}}{\max(\text{GD}_{\text{ANNs}}) + \frac{\min(\text{RMSE}_{\text{ANNs}})}{\text{RMSE}_{\text{model}}}} \quad (9)$$

Figure 4 shows schematic of proposed methodology, also pseudocode is as follow:

```

get Data //include X,Y matrixes
setRMSE_network =1 // beginning of modeling phase
set min_RMSE=0.4
for all kind of neural networks
    while (RMSE_network>min_RMSE or coefficient of correlation<0)
  
```

```

    set X and Y
    if mn_RMSE> RMSE_network
    set min_RMSE=RMSE_network
    end if
    add one to iterations
    end // end of while
end for

calculate CM weights using GA randomly
train network
calculate RMSE_network and coefficient of correlation
if RMSE_network<min_RMSE for goal of minimizing in overall RMSE
calculate CM weights by GA with object minimizing absolute error between y CM and y real for each response separately.
// end of modeling phase
calculate X*1, y*1 and GD(X*1) using GA for goal of maximizing in Global desirability //
  
```

IV. RESULTS AND DISCUSSION

Genetic algorithm is used for finding CM weights with object of object minimizing absolute error between y CM and y real for each response separately. Also GA was used to find final responses with maximum global desirability.

For all of them, GA specifications are as table 2.

TABLE II
GA SPECIFICATION

Variable	Magnitude/Kind	Variable	Magnitude/Kind
Parent population	20	Mutation type	Uniform
Selection Function	Stochastic Uniform	Number of variables	5
Number of elites	2	Number of responses	1
Crossover Fraction	0.8	Migration Direction	'forward'
Crossover Function	Scattered	Migration Fraction	0.2

Five MRO problems were selected to solve with CM. These problems contain different number of inputs and outputs, also

different number of experiments. Their properties are shown in table 3.

TABLE III
CASES PROPERTIES

Case No.	No. of x's (m)	No. of y's (N)	No. of Experiments (r)	Reference	Objects
1	3	6	15	(Noorossana et al., 2008)	T T T T T T
2	4	2	18	(Giordano et al., 2010)	nX
3	3	3	30	(Martinez Delfa et al., 2009)	T T T
4	2	2	13	(Bhatti et al., 2011)	Xn
5	4	4	30	(Aggarwala et al., 2008)	nXnn

T:Target X:Maximum n:Minimum

Case1: The problem is based on the wire-bonding process in the semiconductor industry. The process inputs and outputs have shown in table 4. Different neural networks were made to model data of experiments. These ANNs specifications are listed in table 5. To have better comparison between committee machine and other neural networks, same specifications were considered for all other cases as table VI except case 3, and that was due to get acceptable results. Four

ANNs include feedforward (FF), Radial Base Function (RBF), GRNN and ANFIS were consisted for every response for every problem data. So every problem has found (4*No of responses) models. Consequently, the results of other models are listed in table 6. A committee machine was made with object minimizing absolute error between y CM and y real for each response separately.

TABLE IV
INPUT AND RESPONSE VARIABLES AND OPTIMIZATION CRITERIA FOR EVERY RESPONSE (OUTPUT) IN CASE 1

Input (Independent) Variables	Output(Dependent) Variables	Opt. criteria
x1: Flow rate (SCFM)	y1: Maximum temperature at position A (°C)	Target
x2: Flow temp (°C)	y2: Beginning bond temperature at position A (°C)	Target
x3: Block temp (°C)	y3: Finish bond temperature at position A (°C)	Target
	y4: Maximum temperature at position B (°C)	Target
	y5: Beginning bond temperature at position B (°C)	Target
	y6: Finish bond temperature at position B (°C)	Target

TABLE V
NETWORKS SPECIFICATIONS FOR CASE 1

Response	No. of neurons in hidden and output layer of feed forward	RBF Spread Coef.	GRNN Spread Coef.	ANFIS membership function
y1	3-6-1	0.75	0.55	dsigmf
y2	3-6-1	0.75	0.67	trimf
y3	3-4-1	0.9	0.67	trimf
y4	3-3-1	0.45	0.6	trimf
y5	3-6-1	0.9	0.65	gbellmf
y6	3-3-1	0.66	0.65	gbellmf

Case2: The problem is to optimize the yield of recombinant containing byproduct glycerol. The input and output variables Oryza sativa non-symbiotic hemoglobin 1 in medium have listed in table 7.

TABLE IV
NETWORKS SPECIFICATIONS FOR CASES 2-5 FOR ALL Y'S

Case No.	No. of neurons in hidden and output layer of feed forward	RBF Spread Coef.	GRNN Spread Coef.	ANFIS membership function
2,4,5,6	3-1	0.85	0.5	gbellmf
3	3-5-1	0.85	0.45	gbellmf

TABLE VII
INPUT AND RESPONSE VARIABLES AND OPTIMIZATION CRITERIA FOR EVERY RESPONSE (OUTPUT) (CASE 2)

Input (Independent) Variables	Output(Dependent) Variables	Opt. criteria
x1: Tryptone. (g L ⁻¹) x2: Yeast extract (g L ⁻¹)	y1: Biomass. (g L ⁻¹)	Minimize
x3: Sodium chloride (g L ⁻¹) x4: Byproduct glycerol (g L ⁻¹)	y2: Oryza sativa non-symbiotic hemoglobin1_ OsHb1 (g L ⁻¹)	Maximize

Case3: the problem is multiple response optimization of styrene-butadiene rubber (SBR) emulsion batch polymerization. The input and output variables have listed in table VIII.

TABLE VIII
INPUT AND RESPONSE VARIABLES AND OPTIMIZATION CRITERIA FOR EVERY RESPONSE (OUTPUT) (CASE 3)

Input (Independent) Variables	Output(Dependent) Variables	Opt. criteria
Initiator (mL)	solid content of latex (wt%)	Target
Activator (mL)	Mooney viscosity	Target
Chain transfer agent_CTA (mL)	polydispersity	Target

Case 4: Object of this case is to optimize process variables, electrolysis voltage and treatment time for the electro coagulation removal of hexavalent chromium (Cr(VI)). The input and output variables have listed in table 9.

TABLE IX
INPUT AND RESPONSE VARIABLES AND OPTIMIZATION CRITERIA FOR EVERY RESPONSE (OUTPUT) (CASE 4)

Input (Independent) Variables	Output(Dependent) Variables	Opt. criteria
x1: Voltage(V)	y1: Reduction efficiency (%)	Maximize
x2: Time(min)	y2: Energy consumption (Wh)	Minimize

Case 5: problem is to optimize multiple characteristics in CNC turning of AISI P-20 tool steel using liquid nitrogen as a coolant. The input and output variables have listed in table 10.

TABLE X
INPUT AND RESPONSE VARIABLES AND OPTIMIZATION CRITERIA FOR EVERY RESPONSE (OUTPUT) (CASE 5)

Input (Independent) Variables	Output(Dependent) Variables	Opt. criteria
Cutting speed (m/min)	Surface roughness (μ m)	Minimize
Feed (mm/rev)	Tool life (min)	Maximize
Depth of cut (mm)	Cutting force (N)	Minimize
Nose radius (mm)	Power consumption (W)	Minimize

Table XI represents weights of committee machine in initial approach for case 1 and tables XII and XIII represent these weights in new approach. As mentioned total number of weights is 36 (4*6*15).

TABLE XII
COMMITTEE MACHINES WEIGHTS BY GA IN NEW APPROACH (CASE 1_EXPERIMENTS 1-8)

		no_1	no_2	no_3	no_4	no_5	no_6	no_7	no_8
FF_wights	y1	0.1111	0.006	0.01	0.0695	0.3205	0.9886	0.0504	0.2369
	y2	0.9995	0.999	0.2889	0.1605	0.1192	0.5556	0.1044	0.9908
	y3	0.0001	0.9969	0.1605	0.2148	0.9998	0.3611	1	0.001
	y4	1	0.0364	0.2577	0.0777	0.9999	0.3792	0.1111	0.2
	y5	0.9962	0.8	0.1111	0.1671	0.102	0.0007	0.1583	0.1993
	y6	0.1252	0.0067	0.0285	0.0701	0.0109	0.0383	0.168	0.9346
RBF_wights	y1	0.4444	0.8954	0.286	0.0011	0.3432	0.0017	0.1522	0.0315
	y2	0.0001	0.0006	0.5333	0.3457	0.4394	0	0.4273	0.0001
	y3	0.7604	0.0018	0.3457	0.3704	0	0.4509	0	0
	y4	0	0.2206	0.3426	0.7929	0	0.3104	0.3111	0.2667
	y5	0.0006	0.1728	0.4446	0.4066	0.7505	0.0009	0.4209	0.5101
	y6	0.4417	0.0096	0.1742	0.0313	0.0013	0.633	0.6069	0.0101
GRNN_wights	y1	0	0.0203	0.0815	0.0595	0.1495	0.0084	0.6033	0.0236
	y2	0.0003	0.0001	0	0	0	0	0	0.0017
	y3	0.0829	0.0007	0	0	0	0.1686	0	0
	y4	0	0.702	0	0	0.0001	0	0	0
	y5	0.0028	0.0247	0	0	0.1323	0.0002	0	0
	y6	0.2123	0.0359	0	0	0.02	0.0207	0.0276	0.0315
ANFIS_wights	y1	0.4444	0.0783	0.6224	0.87	0.1868	0.0013	0.1941	0.7081
	y2	0.0001	0.0003	0.1778	0.4938	0.4414	0.4444	0.4683	0.0075
	y3	0.1567	0.0006	0.4938	0.4148	0.0002	0.0194	0	0.9989
	y4	0	0.0411	0.3997	0.1293	0	0.3104	0.5778	0.5333
	y5	0.0004	0.0026	0.4443	0.4263	0.0152	0.9982	0.4209	0.2906
	y6	0.2209	0.9478	0.7974	0.8986	0.9678	0.308	0.1975	0.0239

TABLE XI
COMMITTEE MACHINES WEIGHTS BY GA IN INITIAL APPROACH (CASE 1)

Model	y1	y2	y3	y4	y5	y6
FF	0.0121	1.0000	0.0768	0.0019	0.4402	0.1567
RBF	0.5377	0.0000	0.3966	0.2612	0.0145	0.0400
GRNN	0.0405	0.0000	0.0000	0.0034	0.0007	0.1210
ANFIS	0.4097	0.0000	0.5266	0.7335	0.5447	0.6823

TABLE XIII
COMMITTEE MACHINES WEIGHTS BY GA IN CURRENT APPROACH (CASE 1_EXPERIMENTS 9-15)

		no_9	no_10	no_11	no_12	no_13	no_14	no_15
FF_weights	y1	0	0.4866	0.032	0.017	0.0198	0.7359	0
	y2	0.0017	0	0.9235	0.0306	0.0071	0.2	0.0002
	y3	0.1101	0.993	0.1111	0.4403	0.1322	0.0215	0.1111
	y4	0.1131	0.2	0.9989	0.52	0.0156	0.0001	0.9999
	y5	0.2527	0.0112	0.9772	0.1605	0.0004	0.1383	0.0047
	y6	0.1111	1	0.0713	0.0065	0	1	0.4269
RBF_weights	y1	0.8526	0.333	0.9094	0.4227	0.9098	0.2205	0.3379
	y2	0.7811	0.91	0.0093	0.2242	0.0355	0.5333	0.1529
	y3	0.4447	0.0019	0.4444	0.0025	0.8094	0.0771	0.4444
	y4	0.111	0.2667	0.0004	0.2391	0.0904	0.1558	0
	y5	0.0557	0.6089	0.0165	0.3456	0.1245	0.7915	0.1727
	y6	0.8889	0	0.143	0.0501	0.0744	0	0.2753
GRNN_weights	y1	0.0377	0.1584	0	0.0452	0.0704	0.0377	0.6524
	y2	0.0034	0.0224	0.0383	0	0.8781	0	0.8279
	y3	0.0002	0.0042	0	0.0753	0	0.8387	0
	y4	0.3388	0	0.0001	0	0	0.6819	0
	y5	0	0.1671	0.0059	0.0001	0.735	0	0
	y6	0	0	0.2133	0	0.1226	0	0.2631
ANFIS_weights	y1	0.1098	0.022	0.0585	0.5151	0	0.0058	0.0097
	y2	0.2138	0.0676	0.0289	0.7452	0.0792	0.2667	0.019
	y3	0.445	0.0008	0.4444	0.482	0.0585	0.0628	0.4444
	y4	0.4371	0.5333	0.0006	0.2408	0.894	0.1622	0
	y5	0.6916	0.2128	0.0004	0.4938	0.1401	0.0702	0.8226
	y6	0	0	0.5724	0.9434	0.803	0	0.0347

TABLE IX
COMPARISON RESULTS OF OVERALL RMSE, GD AND PERFORMANCE INDEX OF ALL MODELS (CASE1)

Model	RMSE	Rmin/R	% change in RMSE to CM _i	GD	G/Gmax	% change in GD to CM _i	P Index
CM _{new}	1.90	1.26	-9.6%	0.639	1.03	34.9%	2.29
CM ₀	2.10	1.14	0.0%	0.474	0.76	0.0%	1.90
ANNs Avg	2.65	0.90	26.3%	0.297	0.48	-37.3%	1.38
FF	2.55	0.94	21.4%	0.566	0.91	19.6%	1.85
RBF	2.47	0.97	17.7%	0.000	0.00	-100.0%	0.97
GRNN	3.20	0.75	52.2%	0.000	0.00	-100.0%	0.75
ANFIS	2.39	1.00	13.7%	0.621	1.00	31.1%	2.00

The case 1 is a famous problem in the literature and several researchers investigated different solutions. The premier author of this case was Del Castillo et al. [2]. His approach got the global desirability of 0.306. Another researcher was Ortiz et al. [11]. According to His solution methodology for this problem, the global desirability was 0.408. the third researcher was Nooroassana et al. [11]. He solved this problem with neural network approach. His methodology got GD=0.417. Finally He et al. [30] as last researcher presented GAPS method. It is a hybrid algorithm include coupling of the genetic algorithm (GA) with the pattern search (PS). According to it, the global desirability is equal to 0.363. Table 15 is a comparison of different method to solve problem case 1 and due to the lack of RMSE or MSE for all solutions, just the global desirability is compared. Remark that, current approach tends to show effect of CM with respect to its experts according to table XIV ns superior comparison will happen when both RMSE and GD be available.

TABLE XV
COMPARISON OF DIFFERENT SOLUTIONS FOR CASE 1

Approach	GD
Del Castillo et al.[2]	0.306
Ortiz et al.[11]	0.408
Nooroassana et al.[11]	0.417
HE et al.[30]	0.363
Golestaneh et al. [1]	0.474
Current approach	0.639

For abstract, the weights for other cases have not showed. The results of overall RMSE and global desirability for each case are listed in tables 16 to 19. In these tables minimum overall RMSE and maximum GD are derived from best ANNs. So there is a comparison between any model include ANNs or CMs with best expert

Furthermore, another comparison in these tables are between all models and initial committee machines with respect of change percent in overall RMSE and GD.

It can be seen in all cases overall RMSE decreases and as usual GD has decreasing too. But decreasing percent of RMSE is many more than GD.

As a consequence, It can be seen that all new CMs have superior performance index than all ANNs and initial CM.

TABLE XVI
COMPARISON RESULTS OF OVERALL RMSE, GD AND PERFORMANCE INDEX OF ALL MODELS (CASE2)

Model	RMSE	Rmin/R	% change in RMSE to CM _i	GD	G/Gmax	% change in GD to CM _i	P Index
CM _{new}	0.07	6.72	-76.1%	0.720	0.77	-1.1%	7.49
CM ₀	0.29	1.61	0.0%	0.727	0.78	0.0%	2.39
ANNs Avg	0.54	0.86	86.1%	0.747	0.80	2.7%	1.66
FF	0.67	0.70	128.2%	0.933	1.00	28.3%	1.70
RBF	0.47	1.00	60.7%	0.694	0.74	-4.5%	1.74
GRNN	0.56	0.85	89.9%	0.586	0.63	-19.4%	1.47
ANFIS	0.48	0.97	65.7%	0.774	0.83	6.5%	1.80

TABLE XVII
COMPARISON RESULTS OF OVERALL RMSE, GD AND PERFORMANCE INDEX OF ALL MODELS (CASE3)

Model	RMSE	Rmin/R	% change in RMSE to CM _i	GD	G/Gmax	% change in GD to CM _i	P Index
CM _{new}	0.98	5.62	-74.2%	0.969	0.97	-1.6%	6.60
CM ₀	3.81	1.45	0.0%	0.985	0.99	0.0%	2.44
ANNs Avg	9.53	0.58	150.2%	0.978	0.98	-0.7%	1.56
FF	10.54	0.53	176.7%	0.985	0.99	0.1%	1.51
RBF	5.54	1.00	45.3%	0.998	1.00	1.3%	2.00
GRNN	14.70	0.38	285.9%	0.933	0.93	-5.3%	1.31
ANFIS	7.34	0.75	92.8%	0.995	1.00	1.1%	1.75

TABLE XVIII
COMPARISON RESULTS OF OVERALL RMSE, GD AND PERFORMANCE INDEX OF ALL MODELS (CASE4)

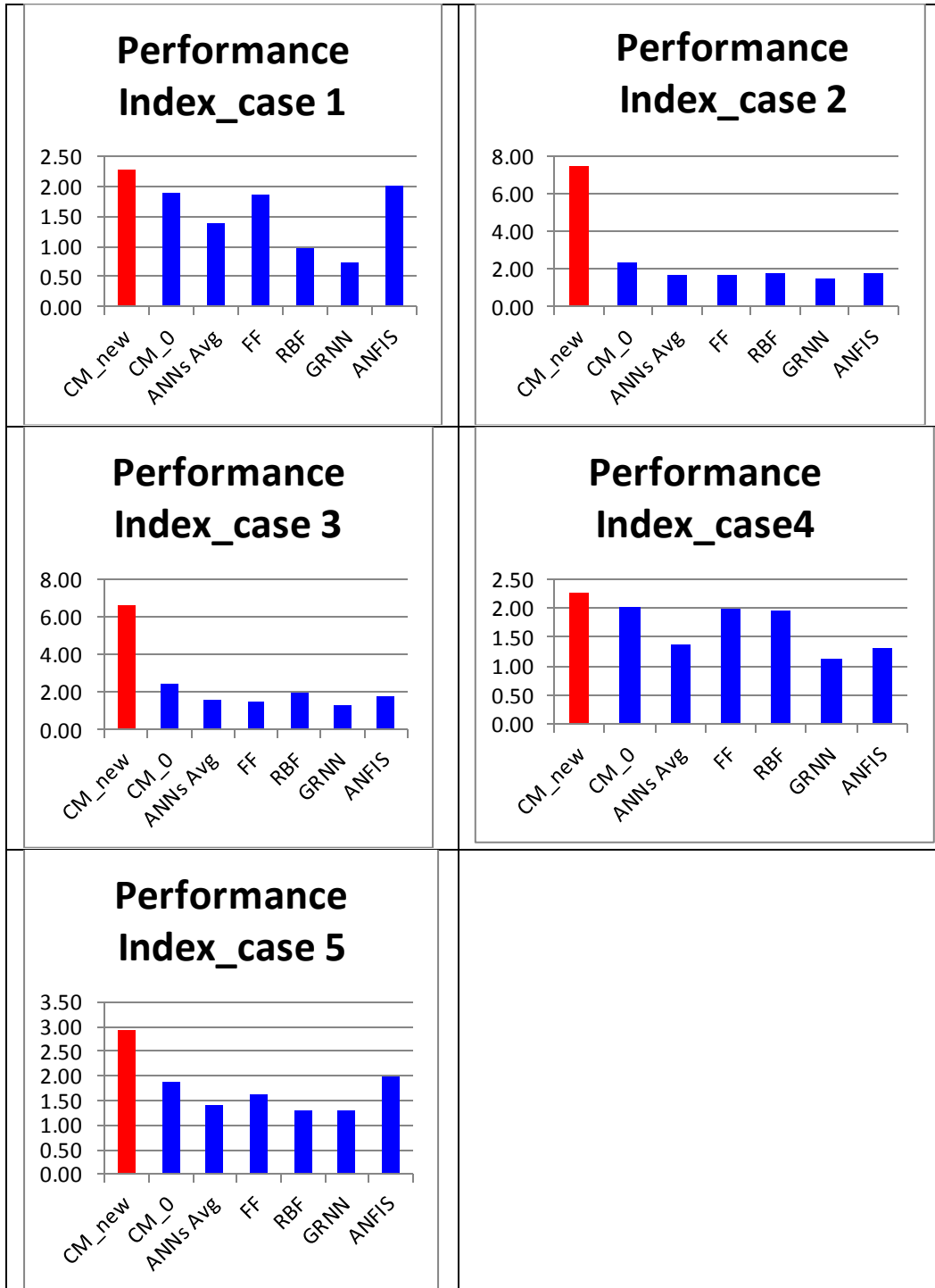
Model	RMSE	Rmin/R	% change in RMSE to CM _i	GD	G/Gmax	% change in GD to CM _i	P Index
CM _{new}	0.35	1.30	-22.2%	0.854	0.97	-4.2%	2.28
CM ₀	0.45	1.01	0.0%	0.891	1.02	0.0%	2.03
ANNs Avg	1.16	0.39	158.8%	0.854	0.98	-4.1%	1.37
FF	0.46	0.99	2.2%	0.876	1.00	-1.8%	1.99
RBF	0.45	1.00	1.5%	0.853	0.97	-4.3%	1.97
GRNN	2.38	0.19	431.6%	0.828	0.95	-7.1%	1.14
ANFIS	1.34	0.34	199.8%	0.861	0.98	-3.4%	1.32

TABLE XIX
COMPARISON RESULTS OF OVERALL RMSE, GD AND PERFORMANCE INDEX OF ALL MODELS (CASE5)

Model	RMSE	Rmin/R	% change in RMSE to CM _i	GD	G/Gmax	% change in GD to CM _i	P Index
CM _{new}	2.00	1.97	-54.3%	0.892	0.98	-1.3%	2.95
CM ₀	4.38	0.90	0.0%	0.904	1.00	0.0%	1.89
ANNs Avg	9.23	0.43	110.9%	0.905	1.00	0.1%	1.42
FF	6.19	0.63	41.6%	0.908	1.00	0.5%	1.63
RBF	13.26	0.30	203.1%	0.904	1.00	0.1%	1.29
GRNN	13.53	0.29	209.1%	0.901	0.99	-0.3%	1.28
ANFIS	3.93	1.00	-10.2%	0.907	1.00	0.4%	2.00

The graphical result for better comparison is presented in table 20.

TABLE XX
 GRAPHICAL COMPARISON OF DIFFERENT MODELS PERFORMANCE FOR ALL FIVE CASES



ACKNOWLEDGEMENT

The authors wish to thank Sadid Industrial Group and especially Eng. A.A. Maghsoudi, for support.

CONCLUSION

Different artificial neural networks (ANNs) are used for modeling of multiple response optimization (MRO) problems.

Committee machine is a collection of several elements or experts such as ANNs. Current study is a development of recent authors work on application of committee machine to solve MRO problem. In current new approach, all weights of CM are calculated by genetic algorithm that its fitness function is minimizing absolute error between CM response and real data for each respons. This new approach yields

noticeable decreasing in overall RMSE of new CM with respect to initial CM. also there is a negligible decreasing in global desirability. But due to higher accuracy of new CM, its performance is superior than previous one. The results of five case studies include target, minimizing and maximizing objects, represent the improvement in committee machine performance with new approach. Current study represents a classic approach of CM to solve MRO furthermore new approach, which causes development in performance of modeling. In this study, all experts was utilized together, and as a future work it can be investigate the priority for each expert. In addition, combination of experts is a good subject to develop this approach. Another area to development of current work is investigation about possibility of overfitting in modeling by committee machines.

REFERENCES

- [1] Golestaneh, S.J., et al., *A committee machine approach to multiple response optimization*. International Journal of the Physical Sciences, 2011. **6**(35): p. 7935 - 7949.
- [2] Del Castillo, E., D.C. Montgomery, and D.R. Mccarville, *Modified desirability function for multiple response optimization*. Journal of quality technology, 1996. **28**(3): p. 337-345.
- [3] Guo, W.-l., et al., *Optimization of fermentation medium for nisin production from Lactococcus lactis subsp. lactis using response surface methodology (RSM) combined with artificial neural network-genetic algorithm (ANN-GA)*. African Journal of Biotechnology, 2010. **9**(38): p. 6264-6272.
- [4] Antony, J., et al., *Multiple response optimization using Taguchi methodology and neuro-fuzzy based model*. Journal of Manufacturing Technology Management, 2006. **17**(7): p. 908-925.
- [5] Chang, H.H., *A data mining approach to dynamic multiple responses in Taguchi experimental design*. Expert Systems with Applications, 2008. **35**: p. 1095–1103.
- [6] Kumanan, S., J.E.R. Dhas, and K. Gowthaman, *Determination of submergrd arc welding process parameters using taguchi method and regression analysis*. Indian Journal of Engineering & Materials Sciences, 2007. **12**: p. 177-183.
- [7] Yao, A.W.L., H.T. Liao, and C.Y. Liu, *A Taguchi and Neural Network Based Electric Load Demand Forecaster*. The Open Automation and Control System Journal, 2008. **1**: p. 7-13.
- [8] Lepadatu, D., et al., *Lifetime Multiple Response Optimization of Metal Extrusion Die*. RAMS 2005 IEEE, 2005.
- [9] Pasandideh, S.H.R. and S.T.A. Niaki, *Multi-response simulation optimization using genetic algorithm within desirability function framework*. Applied Mathematics and Computation, 2006. **175**: p. 366–382.
- [10] Mukherjee, I. and P.K. Ray, *A modified tabu search strategy for multiple-response grinding process optimisation*. International Journal of Intelligent Systems Technologies and Applications, 2008. **4**(1/2): p. 97-122.
- [11] Noorossana, R., S.D. Tajbakhsh, and A. Saghaei, *An artificial neural network approach to multiple-response optimization*. International Journal of Advanced Manufacturing Technology, 2008: p. doi: 10.1007/s00170-008-1423-7.
- [12] Cheng, C.B., C.-J. Cheng, and E.S. Lee, *Neuro-Fuzzy and Genetic Algorithm in Multiple Response Optimization*. Computers and Mathematics with Applications, 2002. **44**: p. 1503-1514.
- [13] Chatsirirungruang, P. and M. Miyakawa, *Application of genetic algorithm to numerical experiment in robust parameter design for signal multi-response problem*. International Journal of Management Science and Engineering Management, 2009. **4**(1): p. 49-59.
- [14] Kamo, T. and C. Dagli, *Hybrid approach to the Japanese candlestick method for financial forecasting*. Expert Systems with Applications, 2009. **36**: p. 5023-5030.
- [15] Celikoglu, H.B., *Application of radial basis function and generalized regression neural networks in non-linear utility function specification for travel mode choice modelling*. Mathematical and Computer Modelling, 2006. **44**: p. 640–658.
- [16] Matlab User's Guide, *Version 2010b*. Neural Network Toolbox. Math Works, USA, 2010.
- [17] Ardil, E. and P.S. Sandhu, *A soft computing approach for modeling of severity of faults in software systems*. International Journal of Physical Sciences, 2010. **5**(2): p. 074-085.
- [18] Bo, J., T. Yuchun, and Z. Yan-Qing *Hybrid SVM-ANFIS for protein subcellular location prediction*. International Journal of Computational Intelligence in Bioinformatics and Systems Biology, 2009. **1**(1): p. 59.
- [19] Ismail, N., et al., *Modified committee neural networks for prediction of machine failure times*, in *The 3rd national intelligent systems and information technology symposium (ISITS 2010)*. 2010: Institute of Advanced Technology (ITMA), Universiti Putra Malaysia (UPM)-Malaysia.
- [20] Kadkhodaie-Ilkhchi, A., M.R. Rezaee, and H. Rahimpour-Bonab, *A committee neural network for prediction of normalized oil content from well log data: An example from South Pars Gas Field, Persian Gulf*. Journal of Petroleum Science and Engineering 2009. **65**: p. 23-32.
- [21] Karimpouli, S., N. Fathianpour, and J. Roohi, *A new approach to improve neural networks' algorithm in permeability prediction of petroleum reservoirs using supervised committee machine neural network*

- (SCMNN). *Journal of Petroleum Science and Engineering*, 2010. **73**: p. 227–232.
- [22] Liang, Y., *Combining neural networks and genetic algorithms for predicting the reliability of repairable systems*. *International Journal of Quality & Reliability Management*, 2008. **25**(2): p. 201-210.
- [23] Tian, L. and A. Noore, *Evolutionary neural network modeling for software cumulative failure time prediction*. *Reliability Engineering & System Safety*, 2005. **87**: p. 45-51.
- [24] Benyounis, K.Y., A.G. Olabi, and M.S.J. Hashmi, *Multi-response optimization of CO2 laser-welding process of austenitic stainless steel*. *Optics & Laser Technology*, 2008. **40**: p. 76-87.
- [25] Chang, H.-H. and Y.-K. Chen, *Neuro-genetic approach to optimize parameter design of dynamic multiresponse experiments*. *Applied Soft Computing*, 2011. **11**: p. 436–442.
- [26] Dixit, U.S. and S. Chandra, *A neural network based methodology for the prediction of roll force and roll torque in fuzzy form for cold flat rolling process*. *International Journal of Advanced Manufacturing Technology*, 2003. **22**: p. 883–889.
- [27] Haghizadeh, A., I. Teang shui, and E. Goudarzi, *Estimation of Yield Sediment Using Artificial Neural Network at Basin Scale*. *Australian Journal of Basic and Applied Sciences*, 2010. **4**(7): p. 1668-1675.
- [28] Krause, P., D.P. Boyle, and F. Base, *Comparison of different efficiency criteria for hydrological model assessment*. *Advances in Geosciences*, 2005. **5**: p. 89–97.
- [29] Banik, S., M. Anwer, and A.F.M. Khodadad Khan, *Predictive Power of the Daily Bangladeshi Exchange Rate Series based on Markov Model, Neuro Fuzzy Model and Conditional Heteroskedastic Model*, in *12th International Conference on Computer and Information Technology (ICCIT 2009)*. 2009: Dhaka, Bangladesh. p. 303-308.
- [30] He, Z. and P.F. Zhu, *A hybrid genetic algorithm for multiresponse parameter optimization within desirability function framework*, in *16th international conference of Industrial engineering and engineering management, IEEE*. 2009, IEEE. p. 612-617.